

- 1. The sun seeking algorithm is driven by a microcontroller. The array follows the sun rain or shine. A GPS tells the microcontroller the latitude, longitude, and time. From this, the sun's azimuth and elevation is computed. The sequence of operation is as follows: parked during the night hours. Adjust to the sun's position at a prescribed time in the morning, follow it through the day, to a end of day time, then re-park the array. Repeat.
- 2. The operational modes, besides the "Run" mode, are "Stopped" and the "Jog" Mode. The latter is for cleaning.
- 3. The motors are 72 RPM synchronous motors, that run from 110 volts.
- 4. In the parked mode, proximity sensors, stop the elevation motion when the array is flat. For the azimuth motion, there are 3 proximity sensors. 2 are at the end of travel, and one is tripped when the array faces south.
- 5. 2 junction boxes are used. The high voltage box includes the pass through of the panel AC output. From this,12 volts is made for the microcontroller. This box also includes relay's to operating the motors. The microcontroller lives in a second low voltage junction box. Limit switches terminate in this box. Motor move signals go to the high voltage box.
- 6. An alternative drive method, is to have a sun intensity sensor move the array toward the hot spot in the sky. A controller for this available at www.theanalogguy.com.

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PARTS LIST								
ITEM	QTY	PART NUMBER	DESCRIPTION	QA		7''''		
1	1	Ground	Ground Column			l <b>.</b>		
2	1	PoleBaseV3	Pole Base	1500 Watt Array				
3	1	OuterColumnV1	Outer Column and Azinuth Drive	- APPROVED		CIZE   DIVIC NO		
4	1	Racking3	Racking and Array	AFFROVED				
5	1	ElMotorMount2	Elevation Drive			SIZE	DWG NO	REV
6	1	ControlBox1	Contains microcontroller,LCD,Keypad,GPS				1500WattAssy	1
7	1	Power box	Contains 220 v,Relays,12v DC to Control Box			SCALE	SHEET 1 OF 4	3
		3	Δ	2			1	

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